
MANIFOLD OPTIMIZATION IN DATA SCIENCE

Max Pfeffer

Networks Seminar

IISc Bangalore

March 3, 2026

MATRIX FACTORIZATIONS

MATRIX FACTORIZATIONS

- Dimensionality Reduction

MATRIX FACTORIZATIONS

- Dimensionality Reduction
- Feature Extraction

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↳ PCA

MATRIX FACTORIZATIONS

- Dimensionality Reduction
- Feature Extraction
- Clustering

MATRIX FACTORIZATIONS

- Dimensionality Reduction
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 - ↳ Unsupervised Learning

MATRIX FACTORIZATIONS

$$M \in \mathbb{R}^{m \times n}$$

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$$X \in \mathbb{R}^{m \times r}$$

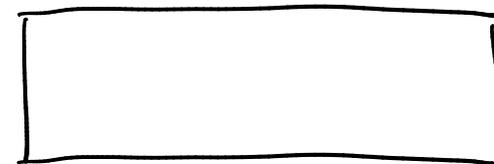
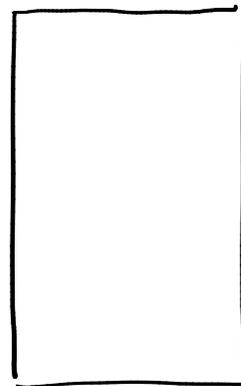
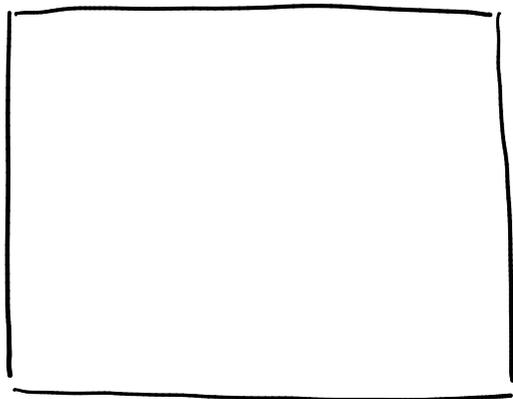
$$Y \in \mathbb{R}^{n \times r}$$

M

=

X

Y^T



MATRIX FACTORIZATIONS

$$M \in \mathbb{R}^{m \times n}$$

$$X \in \mathbb{R}^{m \times r_1} \quad A_i \in \mathbb{R}^{r_i \times r_{i+1}} \quad Y \in \mathbb{R}^{n \times r_2}$$

M

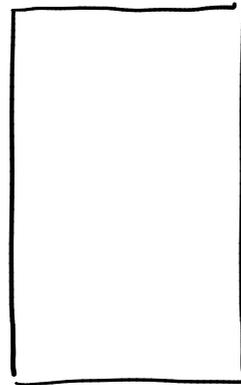
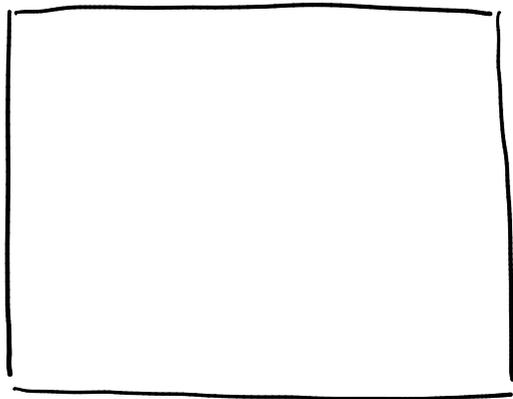
=

X

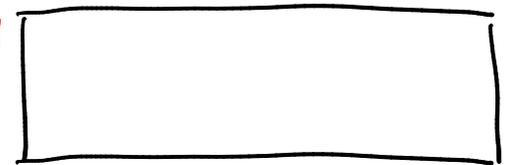
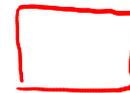
A_1

A_2

Y^T



...



↑
"hidden layers"

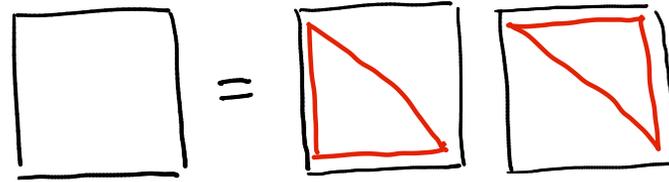
MATRIX FACTORIZATIONS

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• Cholesky decomposition: $M = CC^T$, $M = M^T$



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$$\square = \begin{array}{|c|} \hline \color{red}{\triangle} \\ \hline \end{array} \begin{array}{|c|} \hline \color{red}{\triangle} \\ \hline \end{array}$$

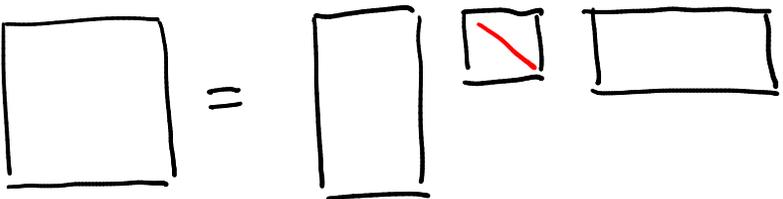
- QR-decomposition: $M = QR$, $Q^T Q = I$

$$\square = \square \begin{array}{|c|} \hline \color{red}{\triangle} \\ \hline \end{array}$$

MATRIX FACTORIZATIONS

Examples:

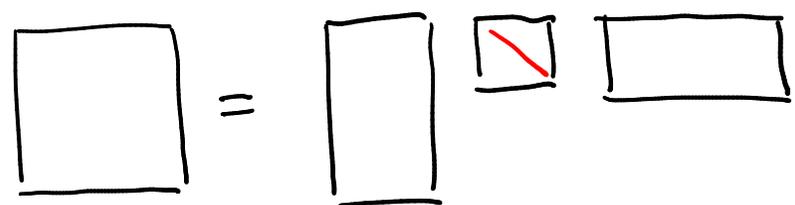
- Singular-value-decomposition:
(SVD)

$$M = U \Sigma V^T, \quad U^T U = V^T V = I$$


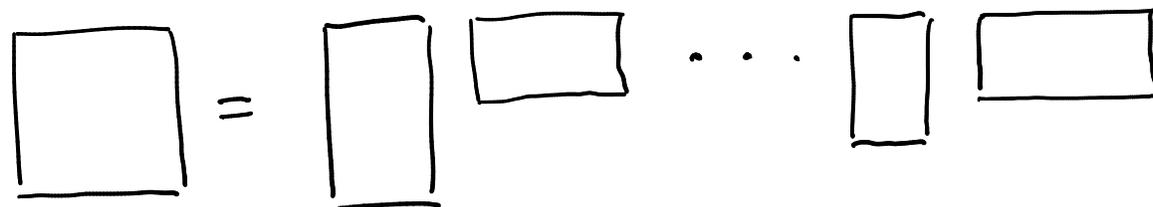
MATRIX FACTORIZATIONS

Examples:

- Singular-value-decomposition:
(SVD)

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- Linear neural network: $M = A_1 \cdots A_e$



TENSOR FACTORIZATIONS

$$T \in \mathbb{R}^{n_1 \times \dots \times n_d}$$

TENSOR FACTORIZATIONS

$$T \in \mathbb{R}^{n_1 \times \dots \times n_d} \longrightarrow \text{order } d$$

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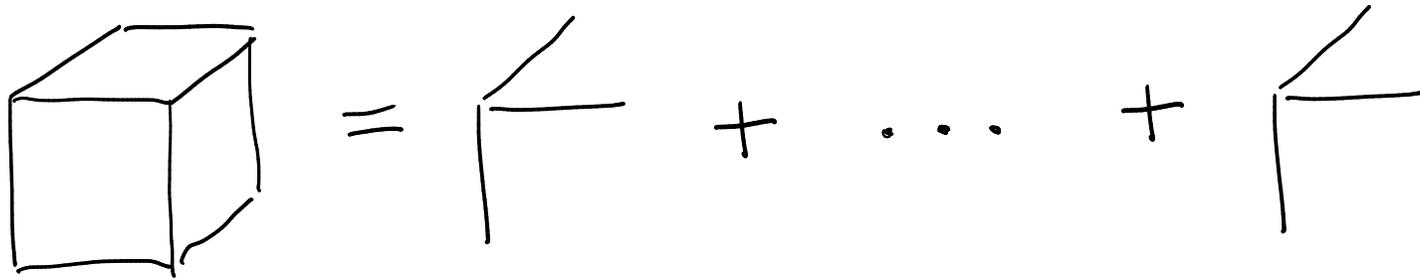
TENSOR FACTORIZATIONS

$$T \in \mathbb{R}^{n_1 \times \dots \times n_d}$$

Formats:

- Canonical Polyadic (CP) decomposition:

$$T = \sum_{i=1}^R u_1^{(i)} \otimes \dots \otimes u_d^{(i)}, \quad u_j^{(i)} \in \mathbb{R}^{n_j}$$



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- not closed

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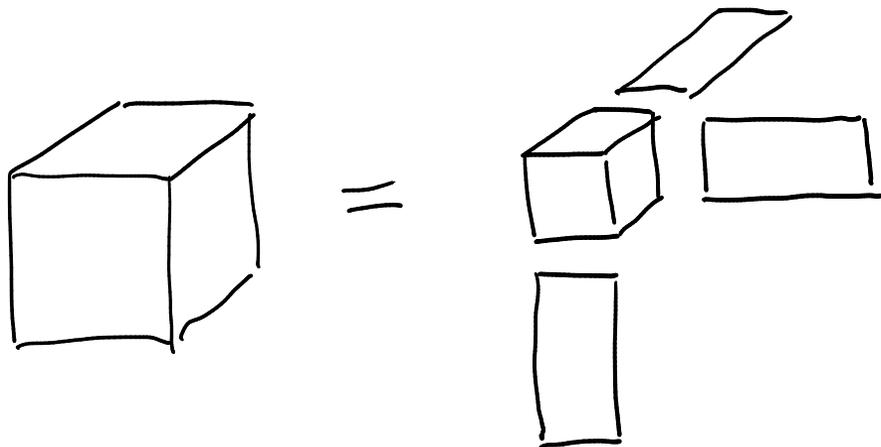
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Formats:

- Tucker decomposition:

$$T = C \circ_1 U_1 \circ_2 U_2 \dots \circ_d U_d, \quad C \in \mathbb{R}^{r_1 \times \dots \times r_d}$$

$U_i \in \mathbb{R}^{n_i \times r_i}$



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- still exponential in d

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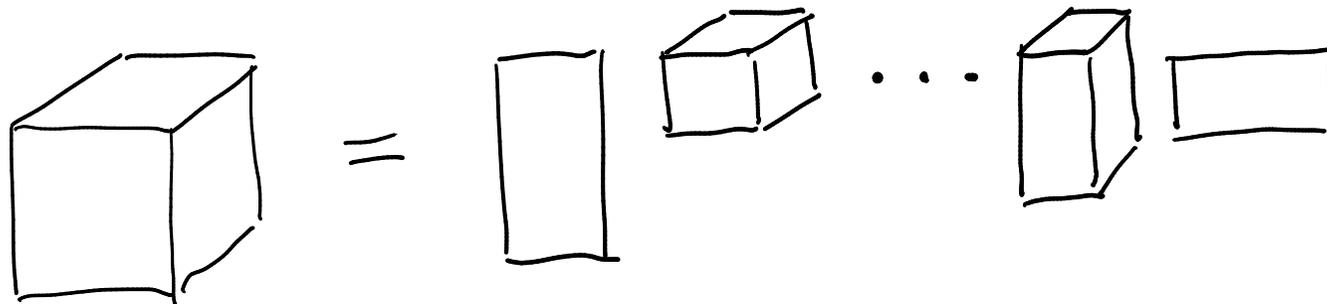
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- Tensor Train (TT) decomposition:

$$T = U_1 \cdot U_2 \cdot \dots \cdot U_d, \quad U_i \in \mathbb{R}^{r_{i-1} \times n_i \times r_i}$$

$r_0 = r_d = 1$



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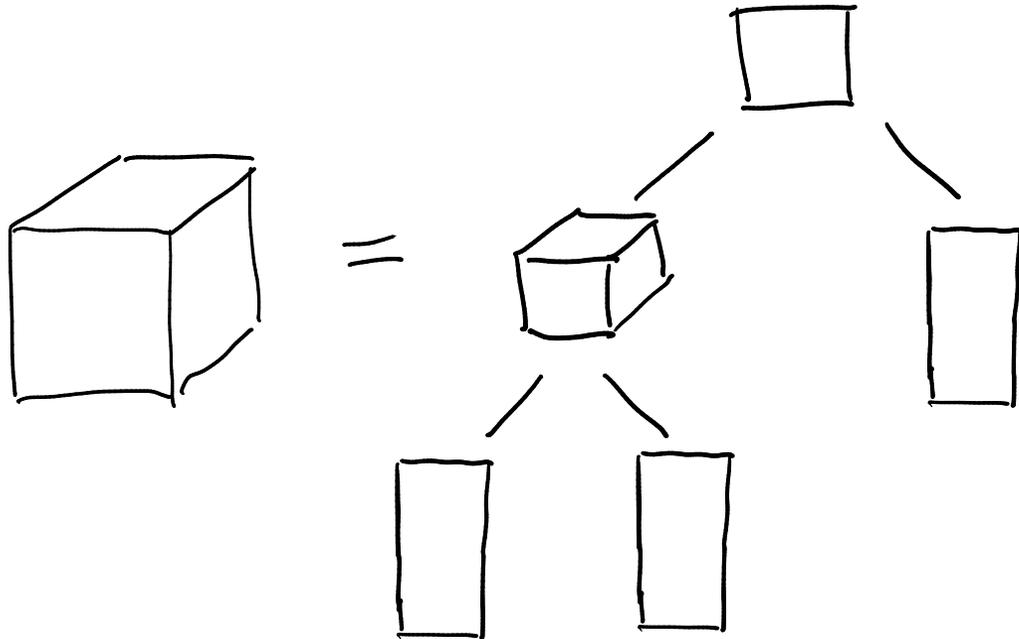
- + better storage than Tucker
- + easy to compute
- + can be made unique
- interpretation not straightforward

TENSOR FACTORIZATIONS

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Formats:

- General tree tensor networks:



JOINT FACTORIZATIONS

Take collection of matrices M_1, \dots, M_k
and/or tensors T_1, \dots, T_L .

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Example: $X = [x_1 \dots x_R]$

$$M = X Y^T, \quad T = \sum_{i=1}^R x_i \otimes u_1^{(i)} \otimes \dots \otimes u_{d-1}^{(i)}$$

CONSTRAINTS

It is often beneficial to impose the factors
with constraints.

CONSTRAINTS

Some examples:

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CONSTRAINTS

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- Orthogonality: $A^T A = I$
 - can enforce uniqueness
 - is a form of independence

CONSTRAINTS

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- Orthogonality : $A^T A = I$
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 - when orthogonality is too much to ask

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 - when the data is also nonnegative

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 - for feature extraction

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- Statistical independence (of the columns)
- many more

THEORETICAL PROBLEMS

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- Computability
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- $\text{rank } M \leq \text{constrained rank } M$

ALGORITHMS

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Some known examples:

- LU-decomposition can be computed **exactly** using the Gauss-algorithm.
- QR can be computed using Householder transformations.
- SVD can be computed **to arbitrary accuracy in polynomial time.**

ALGORITHMS

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General form:

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for each matrix/tensor

ALGORITHMS

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format of the decomposition



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General form:

$$\min \|M - XY^T\|_F^2$$

$X, Y \in S$

subset constraints

ALGORITHMS

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General form:

$$\min_{X, Y} \|M - XY^T\|_F^2 + \lambda g(X, Y)$$

penalty for constraints



ALGORITHMS

Otherwise, we need optimization algorithms.

General form:

$$\min_{X, Y_1, Y_2} \|M_1 - XY_1^T\|_F^2 + \|M_2 - XY_2^T\|$$

joint factorization

ALGORITHMS

Some techniques:

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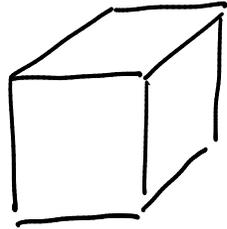
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ALGORITHMS

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Tucker-format

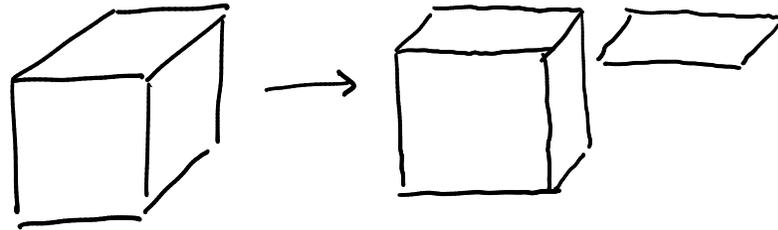


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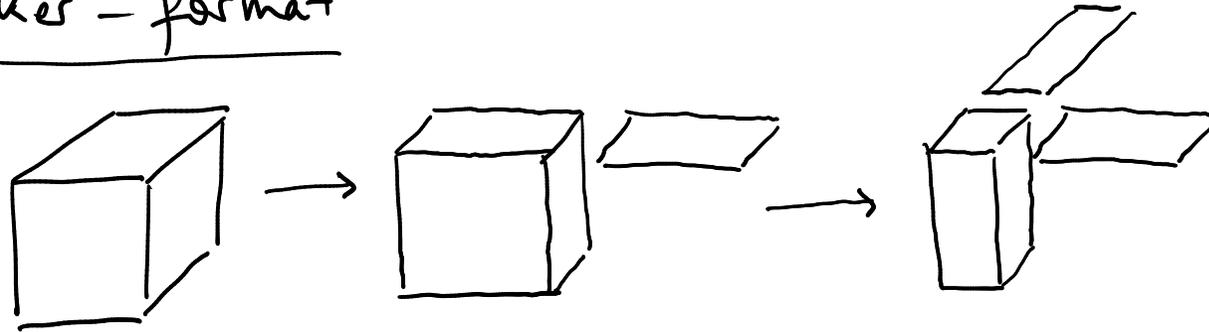


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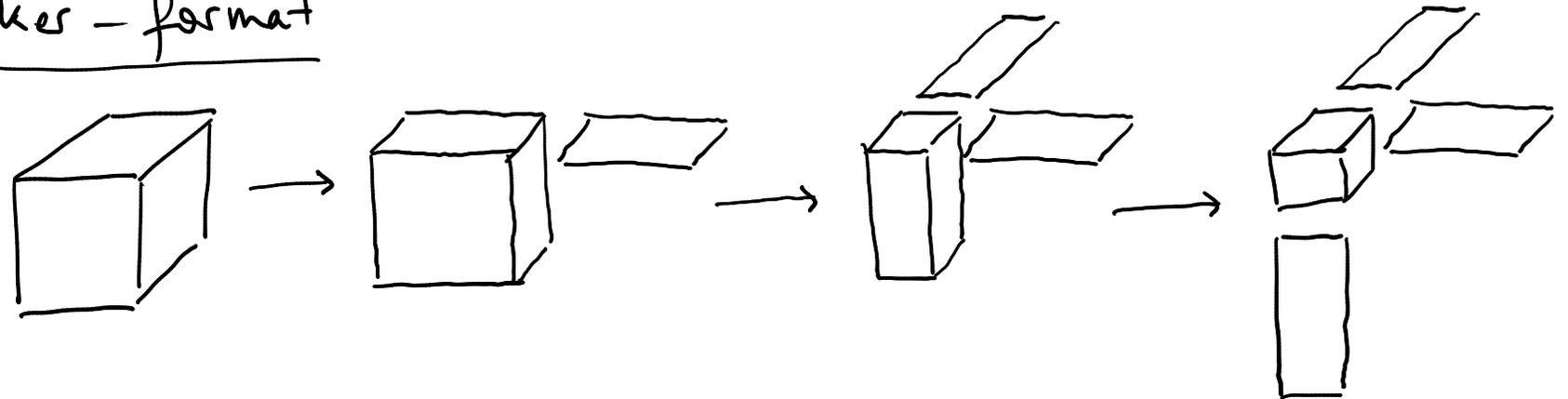


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Fix Y , minimize for X

ALGORITHMS

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$$\min_Y \|M - XY^T\|_F^2$$

Fix X , minimize for Y

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$$\min_x \|M - XY^T\|_F^2$$

↻ repeat

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 - cost will always decrease

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- Alternating least squares (ALS):
 - cost will always decrease
 - convergence to critical point not always guaranteed
 - often fast but can be slow

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→ Riemannian optimization



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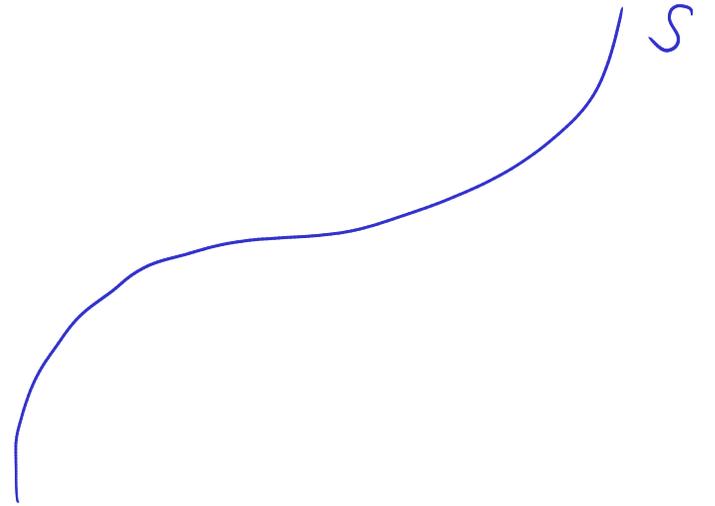
$$\min f(x) \text{ for } x \in S, \text{ e.g. } f(x) = \frac{1}{2} \|M - XY^T\|_F^2$$

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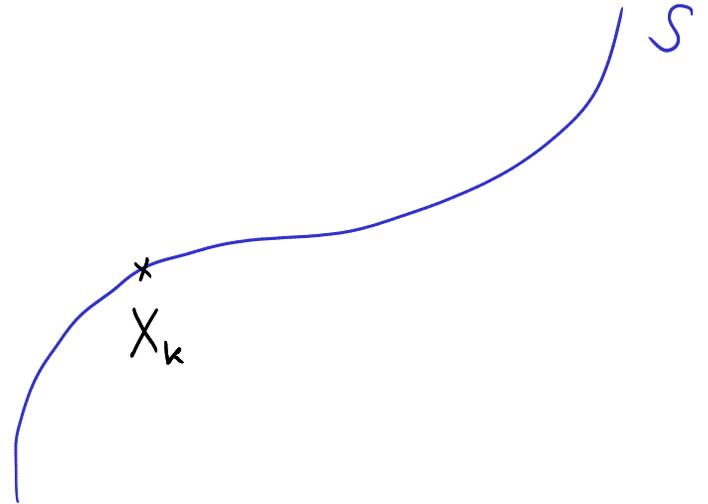


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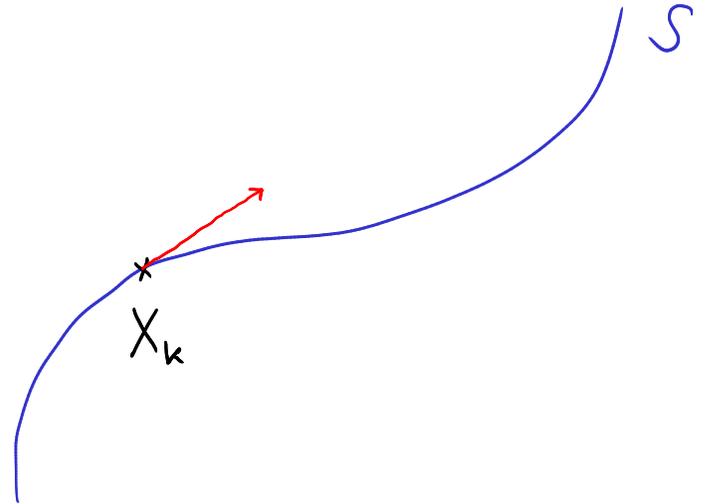
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1. Compute Riemannian gradient

$$\text{grad } f(x_k) \in T_{x_k} S$$



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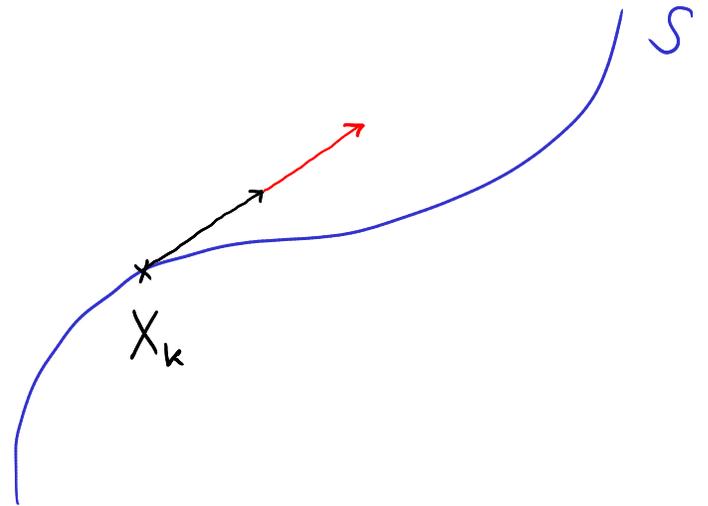
Riemannian manifold

$$\min f(X) \text{ for } X \in \mathcal{S}, \text{ e.g. } f(X) = \frac{1}{2} \|M - XY^T\|_F^2$$

1. Compute Riemannian gradient

$$\text{grad } f(X_k) \in T_{X_k} \mathcal{S}$$

2. Find appropriate stepsize



RIEMANNIAN OPTIMIZATION

If the factors are constrained to a

Riemannian manifold

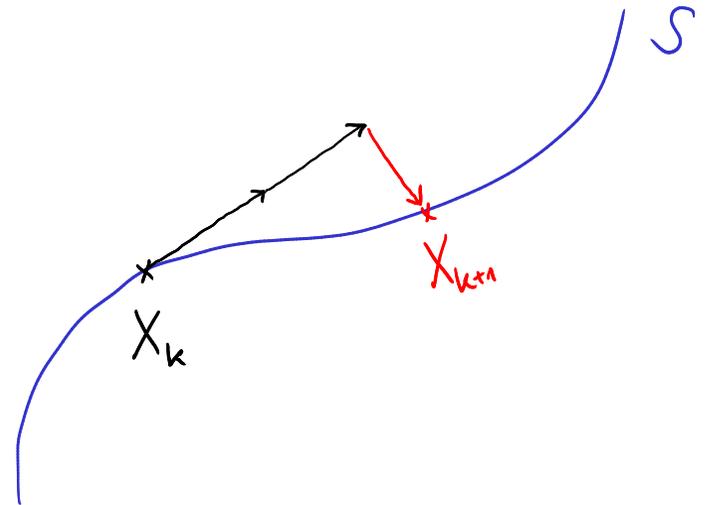
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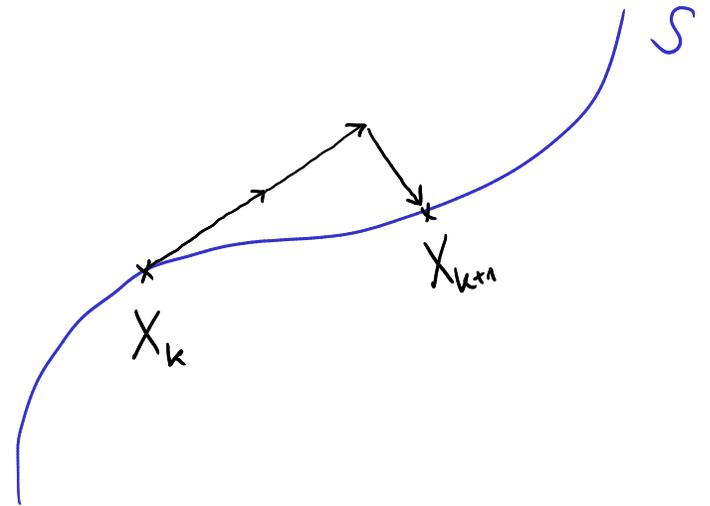
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many
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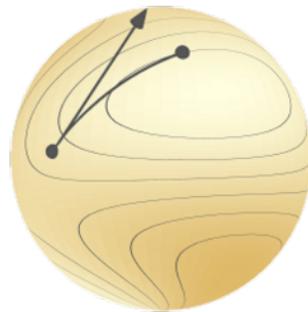
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Manopt

PyManopt

Manopt.jl

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\rightarrow nonsmooth optimization on Riemannian manifolds

APPLICATIONS

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CANCER CLASSIFICATION

Minimization problem:

$$\min \frac{1}{2} \|G - UV_1^T\|_F^2 + \frac{1}{2} \|M - UV_2^T\|_F^2 + \frac{1}{2} \|C - UV_3^T\|_F^2$$

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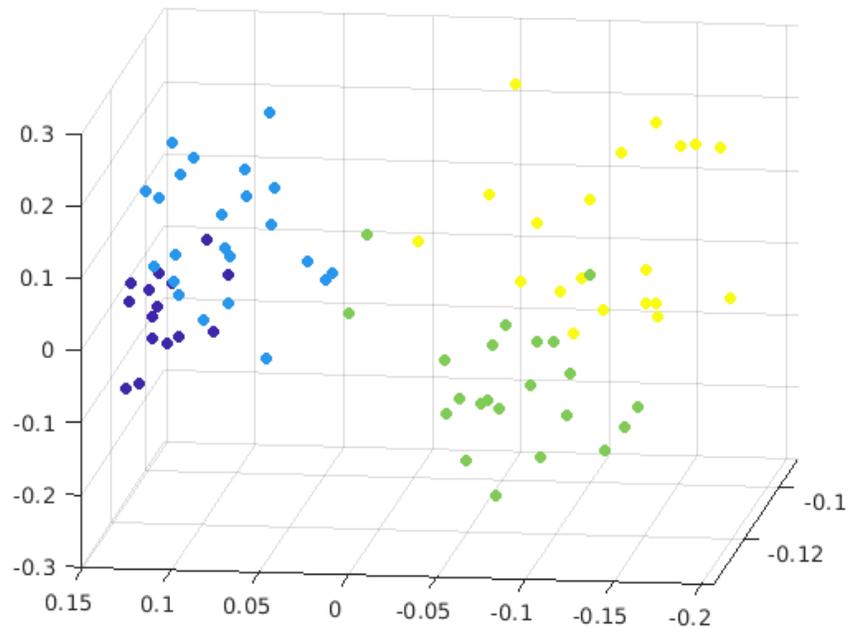
V_1, V_2, V_3 column-normalized

$$U = Z \circ Z, \quad V_1 = W_1 \circ W_1, \quad V_2 = W_2 \circ W_2$$

$$V_3 \in \text{Ob}(n_3, r), \quad W_1 \in \text{Ob4}(n_1, r), \quad W_2 \in \text{Ob4}(n_2, r)$$

CANCER CLASSIFICATION

For uveal melanoma data (TCGA):



First 3 principal components of U matrix

M. Pfeffer, A. Uschmajew, A. Amaro, U. Pfeffer:
Data fusion techniques for the integration of multi-domain genomic data from uveal melanoma.
Cancers, 11 (2019) 10, 1434

A. Amaro, M. Pfeffer, U. Pfeffer, F. Reggiani:
Evaluation and Comparison of Multi-Omics Data Integration Methods for Subtyping of Cutaneous Melanoma.
Biomedicines 10(12) (2022)

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Motivation: • Laplace Operator $L = \Delta \otimes I + I \otimes \Delta$

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Problems:

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• Solution optimal only in Frobenius norm
and not in "norm" given by A

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Alternative approach:

$$\text{Minimize } f(X) = \text{trace}(X^T A(X))$$

$$\text{for } X \in \text{St}(m, n, p) \cap \mathbb{R}_r^{m \times n \times p}$$

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$$\uparrow \text{rank}([X]_m^{np}) = r$$

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transversal intersection

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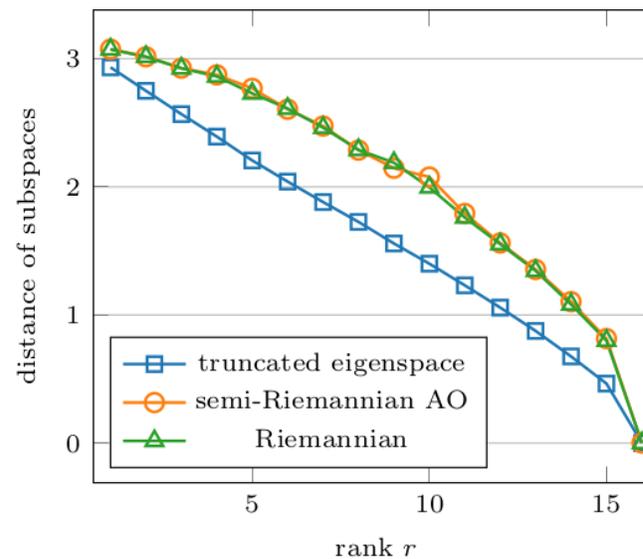
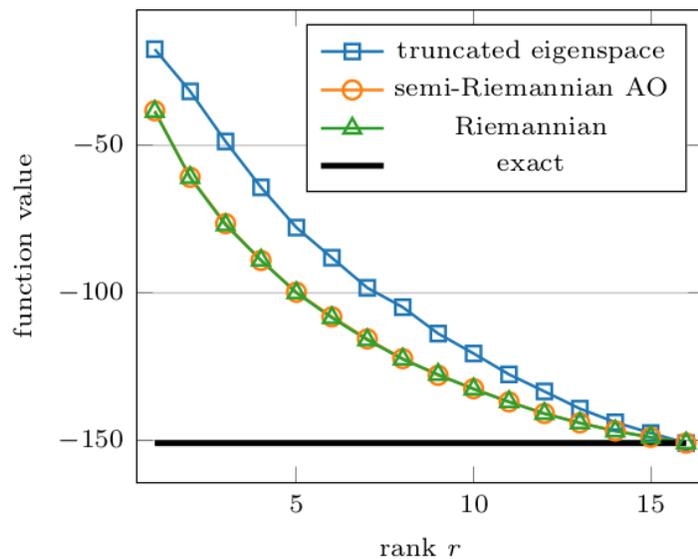
\Rightarrow Riemannian manifold

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C. Krumnow, M. Pfeffer, A. Uschmajew:

Computing eigenspaces with low rank constraints.

SIAM Journal on Scientific Computing, 43 (2021) 1, p. 586-608

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Measurement operator
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Rank- r manifold

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penalty parameter

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Application:

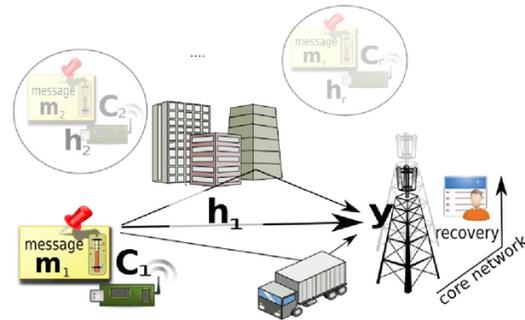
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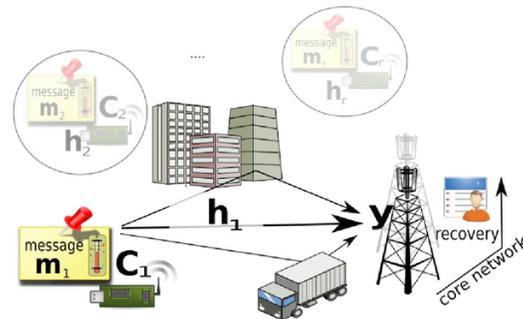
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$$\rightarrow \text{rank}(X) = 1$$

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Riemannian gradient step for $f(X) = \frac{1}{2} \|A(X) - y\|_2^2$

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$$X_{k+1} = \underbrace{\text{prox}_g^{\mathbb{R}^{n \times n}}}_{\text{Proximal map for } g(x) = \lambda \|X\|_{1,2}} (\mathcal{R}_{X_k}(\text{grad } f(X_k)))$$

Proximal map for $g(x) = \lambda \|X\|_{1,2}$

on the low-rank manifold!

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↑ row-soft thresholding

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- slow (so far)

LOW-RANK & ROW-SPARSE RECOVERY

ε	Adaptive IHT		Adaptive RIHT		RPG	
	Iterations	CPU time	Iterations	CPU time	Iterations	CPU time
Random Rank One Measurements						
10^{-1}	196	0.4131s	196	0.2586s	6691	9.5539s
10^{-3}	831	1.7495s	831	1.1103s	11490	16.675s
10^{-5}	1583	3.3613s	1582	2.0928s	16095	23.931s
Fourier Measurements						
10^{-1}	8	0.1455s	10	0.0691s	4211	25.331s
10^{-3}	25	0.4592s	30	0.2189s	8941	58.069s
10^{-5}	45	0.8268s	46	0.3392s	13545	91.412s

H. Eisenmann, F. Kraher, M. Pfeffer, A. Uschmajew:

Riemannian thresholding methods for row-sparse and low-rank matrix recovery.

Numerical Algorithms (2022)

COMPLETELY POSITIVE MATRICES

Let $M \in \mathbb{R}_+^{n \times n}$ be a symmetric nonnegative matrix.

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It turns out: $\mathcal{CP}_n \not\subseteq \mathcal{DNN}_n$ for $n > 4$.

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It turns out: $\mathcal{CP}_n \not\subseteq \text{DNV}_n$ for $n > 4$.

Facts: - Finding X is a co-NP-complete problem.

- For $M \in \partial \mathcal{CP}_5$, X is unique.

- The polynomial equations describing $\partial \mathcal{CP}_5$ have very high degree.

COMPLETELY POSITIVE MATRICES

Minimize

$$f(B) = \|M - (B \circ B)(B \circ B)^T\|_F^2$$

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$$A = \begin{pmatrix} 163 & 108 & 27 & 4 & 4 & 27 & 108 \\ 108 & 163 & 108 & 27 & 4 & 4 & 27 \\ 27 & 108 & 163 & 108 & 27 & 4 & 4 \\ 4 & 27 & 108 & 163 & 108 & 27 & 4 \\ 4 & 4 & 27 & 108 & 163 & 108 & 27 \\ 27 & 4 & 4 & 27 & 108 & 163 & 108 \\ 108 & 27 & 4 & 4 & 27 & 108 & 163 \end{pmatrix}$$

COMPLETELY POSITIVE MATRICES

$$B = \begin{pmatrix} \sqrt{27} & \frac{51}{\sqrt{27}} & \sqrt{27} & 0 & 0 & 0 & 0 & \sqrt{\frac{2}{3}} & 0 & 0 & \sqrt{6} & \sqrt{6} & 0 & 0 \\ 0 & \sqrt{27} & \frac{51}{\sqrt{27}} & \sqrt{27} & 0 & 0 & 0 & 0 & \sqrt{\frac{2}{3}} & 0 & 0 & \sqrt{6} & \sqrt{6} & 0 \\ 0 & 0 & \sqrt{27} & \frac{51}{\sqrt{27}} & \sqrt{27} & 0 & 0 & 0 & 0 & \sqrt{\frac{2}{3}} & 0 & 0 & \sqrt{6} & \sqrt{6} \\ 0 & 0 & 0 & \sqrt{27} & \frac{51}{\sqrt{27}} & \sqrt{27} & 0 & \sqrt{6} & 0 & 0 & \sqrt{\frac{2}{3}} & 0 & 0 & \sqrt{6} \\ 0 & 0 & 0 & 0 & \sqrt{27} & \frac{51}{\sqrt{27}} & \sqrt{27} & \sqrt{6} & \sqrt{6} & 0 & 0 & \sqrt{\frac{2}{3}} & 0 & 0 \\ \sqrt{27} & 0 & 0 & 0 & 0 & \sqrt{27} & \frac{51}{\sqrt{27}} & 0 & \sqrt{6} & \sqrt{6} & 0 & 0 & \sqrt{\frac{2}{3}} & 0 \\ \frac{51}{\sqrt{27}} & \sqrt{27} & 0 & 0 & 0 & 0 & \sqrt{27} & 0 & 0 & \sqrt{6} & \sqrt{6} & 0 & 0 & \sqrt{\frac{2}{3}} \end{pmatrix}$$

THANK YOU !